

## DYNAMIXEL MX-106T

### \*\*Cautions

- MX-106T supports TTL communication.
- Recommended voltage of MX-106 is different with that of former EX-106+  
(Operating Voltage : 10~ 14.8V (Recommended Voltage 12V))

### \*\* DESCRIPTION

- DYNAMIXEL is a robot exclusive smart actuator with fully integrated DC Motor + Reduction Gearhead + Controller + Driver + Network in one DC servo module.
- MX series is a new concept of DYNAMIXEL with advanced functions like precise control, PID control, 360 degree of position control and high speed communication.

### \*\* CHARACTERISTIC

- Advanced durability, degree of precision, and wider control zone were achieved thanks to newly applied [CONTACTLESS ABSOLUTE ENCODER](#)
- [360° POSITION CONTROL](#) without dead zone
- [4,096 PRECISE RESOLUTION by 0.088°](#)
- [SPEED CONTROL at ENDLESS TURN MODE](#)
- Reliability and accuracy were advanced in the position control through [PID CONTROL](#)
- High baud rate up to [3Mbps](#)
- [TTL LEVEL COMMUNICATION](#)
- [Torque control via current sensing](#)
- [Supports dual mode for master/slave method](#)
- [Uses aluminum case](#)

\*\*The assembly structure of the MX-106 and EX-106 are the same but there some modifications to the case.\*\*

## MX-106 External Improvements



### \*\* INCLUDES

Description		Qty
DYNAMIXEL	MX-106T	1
HORN	HN05-N101 (MX Exclusive)	1
WASHER	Thrust Washer	1
CABLE	4P Cable 200mm	1
BOLT/NUT	Wrench Bolt M2.5*4	16pcs
	Wrench Bolt M3*8	1pcs
	Nut M2.5	18pcs

**\*\* H/W SPECS**

<b>Product Name</b>	<b>MX-106T</b>		
<b>Weight</b>	153g		
<b>Dimension</b>	40.2mm x 65.1mm x 46mm		
<b>Gear Ratio</b>	225 : 1		
<b>Operation Voltage (V)</b>	10	12	14.8
<b>Stall Torque (N.m)</b>	<b>8.0</b>	<b>8.4</b>	<b>10.0</b>
<b>Stall Current (A)</b>	4.8	5.2	6.3
<b>No Load Speed (RPM)</b>	<b>41</b>	<b>45</b>	<b>55</b>
<b>Motor</b>	<b>Maxon Motor</b>		
<b>Minimum Control Angle</b>	<b>About 0.088° x 4,096</b>		
<b>Operating Range</b>	Actuator Mode : 360° Wheel Mode : Endless turn (Position Control)		
<b>Operating Voltage</b>	<b>10~14.8V (Recommended voltage : 12V)</b>		
<b>Operating Temperature</b>	-5°C ~ 80°C		
<b>Command Signal</b>	Digital Packet		
<b>Protocol</b>	Half duplex Asynchronous Serial Communication (8bit, 1stop, No Parity)		
<b>Link (physical)</b>	<b>TTL Multi Drop Bus</b> (daisy chain type connector)		
<b>ID</b>	254 ID (0-253)		
<b>Baud Rate</b>	8000bps ~ 3Mbps		
<b>Feedback Functions</b>	Position, Temperature, Load, Input Voltage, <b>Current</b> , etc.		
<b>Material</b>	Case : Engineering Plastic Gear : Full Metal		
<b>Position Sensor</b>	<b>Contactless absolute encoder</b>		
<b>Default</b>	<b>ID #1 - 57600bps</b>		

\*\* After purchase, please change ID and baud rate according to your use.

**\*\* COMPATIBLE PRODUCTS**

- Controller : CM-5, CM-510, CM-530, CM-700
- Interface(I/F) : USB2Dynamixel (TTL)
- **NOTICE : Not compatible with the EX-106 horn. (HN05-N101 Set / T101 Set)**

**\*\* CONTROLLING ENVIRONMENT**

- Software for Dynamixel control : ROBOPLUS - [Download](#)
- C/C++, C#, Labview, MATLAB, Visual Basic et. : Library - [Download](#)

**\*\*[Click here to download 2D and 3D drawings](#)**

**\*\*[Click here to go to e-Manual.](#)**